Grab an attendance sheet



Lecture 11 March 11, 2025

TODAY

- A variety of things to look out for to increase chance of success
- Across industrial design, electronics design, power, FW

Disclaimer: I'll be showing some "issues" with 2024 project. This isn't meant to criticize them. They did great! But we can continue to do better!

Electrical connections

Don't use hookup wires + header pins





Electrical connections

Use cables + connectors instead

More robust Easier/faster/more reliable assembly/disassembly

Electrical connections

Common cabling/connector specs

- Number of conductors
- Voltage & current ratings
- Frequency
- Temperature
- Pitch
- Plating
- Insertion force
- SMT, thru-hole, panel mount, etc.
- Locking, polarized, keyed

Nothing in our projects is too crazy. Take the win!

Some cable approaches need special tooling to create Beware!

Disambiguating connectors

If you have 12 2x2 connectors in your system

• What cable goes to what?

You can use

- Keying
- Polarization
- Color



Keyed connectors



Locking connectors

- Vibration happens
- Not avail in 2x2 (4-pin) configuration (I think)





Locking connectors

• There are plenty of other types of locking connectors





RJ11 jack \$0.109@150



Locking connectors

• There are plenty of other types of locking connectors





RJ11 jack \$0.109@150

One cable many connectors

- IDC can do multiple connectors with one cable
- Why have a bunch of I2C cables when they all share same SDA, SCL, PWR, GND



Connectors up or side

- Connectors can "vertical" (point up) or be "right angle"
- Almost any connector



More connectors



Define the physical/electrical interface

• Cabling will ONLY work if connectors on different boards correspond



Where does happiness lie?

- You get exactly what you want
- And nothing else (to eat your power)

It's fine (preferable, actually) to use breakout boards for prototyping

But final product should use your own boards*

*Unless there's some crazy part that is too hard to deal with

• Be careful in choosing the ESP32-C3 chip









ESP32-C3 chip

ESP32-C3 MINI-1 module

ESP32-C3-WROOM-02 module

• Be careful in choosing the ESP32-C3 pins



Table 3: Pin Definitions

Name	No.	Type ¹	Function	
3V3	1	Р	Power supply	
EN	2	I	High: on, enables the chip.	
			Low: off, the chip powers off.	
			Note: Do not leave the EN pin floating.	
104	3	I/0/T	GPIO4, ADC1_CH4, FSPIHD, MTMS	
105	4	I/0/T	GPI05, ADC2_CHO, FSPIWP, MTDI	
106	5	I/0/T	GPIO6, FSPICLK, MTCK	
107	6	I/0/T	GPI07, FSPID, MTDO	
108	7	I/0/T	GPI08	
109	8	I/0/T	GPI09	
GND	9,19	Р	Ground	
1010	10	I/0/T	GPIO10, FSPICSO	
RXD	11	I/0/T	GPIO20, UORXD	
TXD	12	I/0/T	GPIO21, UOTXD	
IO18	13	I/0/T	GPIO18, USB_D-	
1019	14	I/0/T	GPIO19, USB_D+	
103	15	I/0/T	GPIO3, ADC1_CH3	
102	16	I/0/T	GPIO2, ADC1_CH2, FSPIQ	
IO1	17	I/0/T	GPIO1, ADC1_CH1, XTAL_32K_N	
100	18	I/0/T	GPIOO, ADC1_CHO, XTAL_32K_P	

¹ P: power supply; I: input; O: output; T: high impedance.

- Be careful in choosing the ESP32-C3 pins
- Figure out what pins/peripherals you need
 - USB, I2C, SPI, UART, ADCs, GPIOs, etc.
- Watch out for strapping pins
- Map those early!
- Make sure you have enough pins!

Table 3: Pin Definitions

Name	No.	Type ¹	Function
3V3	1	Р	Power supply
EN	2	I	High: on, enables the chip.
			Low: off, the chip powers off.
			Note: Do not leave the EN pin floating.
104	3	I/0/T	GPIO4, ADC1_CH4, FSPIHD, MTMS
105	4	I/0/T	GPIO5, ADC2_CHO, FSPIWP, MTDI
106	5	I/0/T	GPIO6, FSPICLK, MTCK
107	6	I/0/T	GPI07, FSPID, MTDO
108	7	I/0/T	GPI08
109	8	I/0/T	GPI09
GND	9,19	Р	Ground
1010	10	I/0/T	GPIO10, FSPICSO
RXD	11	I/0/T	GPIO20, UORXD
TXD	12	I/0/T	GPIO21, UOTXD
IO18	13	I/0/T	GPIO18, USB_D-
IO19	14	I/0/T	GPIO19, USB_D+
103	15	I/0/T	GPIO3, ADC1_CH3
102	16	I/0/T	GPIO2, ADC1_CH2, FSPIQ
IO1	17	I/0/T	GPIO1, ADC1_CH1, XTAL_32K_N
100	18	I/0/T	GPIOO, ADC1_CHO, XTAL_32K_P

¹ P: power supply; I: input; O: output; T: high impedance.

Realizing on Apr 15 that you don't have enough pins



- Build in time for two revisions
- It takes ~1 week to go from Gerbers to boards in hand
 - Plus time needed to do schematic design, layout, reviews, assembly, test
- One suggested schedule
 - Rev 1: board files ready Fri Mar 21
 - Rev 2: board files ready Fri Apr 11
- It is possible to have JLC do assembly in addition to fab
 - They will do better soldering than you...
 - Will save you assembly + test time *BUT*
 - Takes ~1 extra week [they quote 24-48h...]
 - You must design to the parts they have on hand
 - Or will need to assemble those parts

- Assembly + test
 - Make sure to build in time for this
 - Create test jigs + FW to make it easy to test boards
 - Test all the bits and pieces of each board

• Manufacturers have many resources to help you succeed



Manufacturers have many resources to help you succeed

PCB Layout Design

[中文]

This chapter introduces the key points of how to design an ESP32-C3 PCB layout using an ESP32-C3 module (see Figure ESP32-C3 Reference PCB Layout) as an example.



Manufacturers have many resources to help you succeed

The DNA of tech.

Designing the VEML7700 Into an Application

MECHANICAL CONSIDERATIONS AND WINDOW CALCULATION FOR THE VEML7700

The ambient light sensor will be placed behind a window or cover. The window material should be completely transmissive to visible light (400 nm to 700 nm). For optimal performance the window size should be large enough to maximize the light irradiating the sensor. In calculating the window size, the only dimensions that the design engineer needs to consider are the distance from the top surface of the sensor to the outside surface of the window and the size of the window. These dimensions will determine the size of the detection zone.

First, the center of the sensor and center of the window should be aligned. The VEML7700 has an angle of half sensitivity of about \pm 55°, as shown in the figure below.



Fig. 17 - Relative Radiant Sensitivity vs. Angular Displacement



Remark:

This wide angle and the placement of the sensor as close as possible to the cover is needed, if it should show comparable results to an optometer, which also detects light reflections from the complete surroundings.

Put testpoints everywhere

- Especially on
 - Unused GPIOs
 - Pins you have >1% chance of wanting to connect differently
 - EN pins, for example













- Jumpers for connections that you
 - Want to specify later on
 - Might want to change







- Jumpers for connections that you
 - Want to specify later on
 - Might want to change



It's a good idea to put in a header wherever you want to use Joulescope to measure current



Unassembled parts

- Components in parallel can be placed without being assembled
- Put in a pull-down and pull-up resistor, choose which one to use later on
- Put in I2C pull-ups on each sensor board, only assemble on one



pull-ups

- When something goes wrong...what do you do?
- LEDs
- Displays
- SD cards
- Connectors

No data on dashboard

Is battery dead? Sensor disconnected? Not getting on WiFi? MCU crash? Some other issue?



- When something goes wrong...what do you do?
- LEDs
- Displays
- SD cards
- Connectors

No data on dashboard

Is battery dead? Sensor disconnected? Not getting on WiFi? MCU crash? Some other issue?



- When something goes wrong...what do you do?
- LEDs
- Displays
- SD cards
- Connectors

• When something goes wrong...what do you do?





Light	Status
Off	 Sonos product is not receiving power. Ensure the power cable is fully inserted into the speaker and a working outlet and then check the Sonos app again. Sonos product is functioning properly and the light is disabled. From the Settings tab, tap System and select your product's room name. Locate Status Light to enable or disable the LED.
Solid White	 Sonos product is powered up and functioning properly. If your product is not visible in the Sonos app, click <u>here</u> to add it back.
Flashing White	Sonos product is booting up after being plugged into power. Sonos product is waiting to receive an IP address from the router.
Solid Green	Sonos product is muted.Use the Sonos app or volume buttons on the product to increase volume.
Flashing Green	Sonos product is powered on and ready to be set up.
Solid Orange	Sonos product is powered on and was unable to complete setup. • Reboot your Sonos product. Sonos product is overheating. • Turn off your Sonos product and allow it to cool down before attempting to power it back on. • If light remains solid gragge contact Sonos Customer Care

One RGB LED with color+blinking

- When something goes wrong...what do you do?
- LEDs



LED Activity	Status
Double flashing green	You have an unread message.
Flashing green	The device is in expedition mode.
Flashing red	The device does not have a clear view of the sky.
	The device is below 10% battery power.
Alternating red and green	The device is in SOS mode.
- When something goes wrong...what do you do?
- LEDs To conserve power, do not have an LED on all the time

Blinking is ok (great, actually)

Blink frequently enough that it's not annoying (<30 sec? <15 sec?)

Use colors that are easy to see outdoors

Each LED requires a hole in your enclosure...

Or have a way of triggering debug mode

• When something goes wrong...what do you do?

Displays
I.54'' E-Paper
200x200
200x200
Image: Comparison of the static power
OK for MITOS Probably not worth it for Bike lane

- When something goes wrong...what do you do?
- SD cards
 - Simplest ones are basically just SPI interface to ESP32
 - SD_MMC also exists (faster, more pins) but not avail via Arduino on ESP32-C3
 - Easy tutorials online



- When something goes wrong...what do you do?
- SD cards
 - How will you log?
 - Write a function to write custom messages to SD card

```
// This calls a function that appends
// char* msg to the file denoted in char* path
log_SD(path, msg);
void log_SD(char * path, char * message) {
    open file on SD card
    print messsage to file
    close file on SD card
}
```

- When something goes wrong...what do you do?
- SD cards
 - How will you log?
 - Write a function to write custom messages to SD card

```
void setup() {
 Serial.begin(9600); //begin serial
  // while (!Serial) {
         delay(100);
  11
  // }
  Wire.begin(I2C_SDA, I2C_SCL);
  if (! sht4.begin()) {
    Serial.println("Couldn't find SHT4x");
    while (1) delay(1);
  sht4.setPrecision(SHT4X HIGH PRECISION);
  sht4.setHeater(SHT4X NO HEATER);
Serial.println("Found SHT4x sensor");
Serial.print("Serial number 0x");
Serial.println(sht4.readSerial(), HEX);
  WiFi.begin(network, password);
  //if using channel/mac specification for crowded bands use the
  //WiFi.begin(network, password, channel, bssid);
  uint8 t count = 0; //count used for Wifi check times
Serial.print("Attempting to connect to ");
Serial.println(network);
  while (WiFi.status() != WL CONNECTED && count < 6) { //can chan
    delay(500);
    Serial.print(".");
    count++;
```

- When something goes wrong...what do you do?
- SD cards
 - How will you log?
 - Write a function to replace all of your logging

```
mylog(path, msg);
```

```
// Could also include Serial.println in
// that function
void mylog(char * path, char * message) {
    open file on SD card
    print message to file
    print message to Serial
    close file on SD card
```

- When something goes wrong...what do you do?
- SD cards
 - Still missing plenty of info

rst:0x1 (POWERON_RESET),boot:0x13 (SPI_FAST_FLASH_BOOT) configsip: 0, SPIWP:0xee clk_drv:0x00,q_drv:0x00,d_drv:0x00,cs0_drv:0x00,hd_drv:0x00,wp_drv:0x00 mode:DIO, clock div:1 load:0x3fff0030,len:1184 load:0x40078000,len:13260 load:0x40080400,len:3028 entry 0x400805e4

When something goes wrong...w

- SD cards
 - Still missing plenty of info

```
// Fix mount issue - sdWait fail ignored before command GO_IDLE_STATE
digitalWrite(card->ssPin, LOW);
if (!sdWait(pdrv, 500)) {
 log_w("sdWait fail ignored, card initialize continues");
}
if (sdCommand(pdrv, GO_IDLE_STATE, 0, NULL) != 1) {
  sdDeselectCard(pdrv);
 log_w("GO_IDLE_STATE failed");
  goto unknown_card;
}
sdDeselectCard(pdrv);
token = sdTransaction(pdrv, CRC_ON_OFF, 1, NULL);
if (token == 0x5) {
  //old card maybe
  card->supports_crc = false;
} else if (token != 1) {
 log_w("CRC_ON_OFF failed: %u", token);
  goto unknown_card;
if (sdTransaction(pdrv, SEND_IF_COND, 0x1AA, &resp) == 1) {
  if ((resp & 0xFFF) != 0x1AA) {
    log_w("SEND_IF_COND failed: %03X", resp & 0xFFF);
    goto unknown_card;
  if (sdTransaction(pdrv, READ_OCR, 0, &resp) != 1 || !(resp & (1 << 20))) {
    log_w("READ_OCR failed: %X", resp);
    goto unknown_card;
```

- When something goes wrong...what do you do?
- SD cards
 - How will you log?
 - Utilize native ESP32 logging library, direct to Serial or SD
 - If you could get this to work, would get *all* log messages

SEP-IDF Programming Guide		
SPRESSIF		
	ESP32-C3	~
	stable (v5.4)	~
Search docs		
Get Started		
API Reference		
API Co	PI Conventions	
Application Protocols		
Bluetooth® API		
Error Codes Reference		
Networking APIs		
Peripherals API		

✤ » API Reference » System API » Logging library

Logging library

[中文]

Overview

The logging library provides three ways for setting log verbosity:

- At compile time: in menuconfig, set the verbosity level using the option CONFIG_LOG_DEFAULT_LEVEL.
- Optionally, also in menuconfig, set the maximum verbosity level using the opt CONFIG_LOG_MAXIMUM_LEVEL. By default, this is the same as the default be set higher in order to compile more optional logs into the firmware.
- At runtime: all logs for verbosity levels lower than CONFIG_LOG_DEFAULT_L enabled by default. The function esp_log_level_set() can be used to set a logg

Redirect ESP32 log messages to SD card

https://community.platformio.org/t/redirect-esp32-logmessages-to-sd-card/33734/8 0

• When something goes wrong...what do you do?

SD cards

- You can adjust the SPI bus frequency
- Consider write size
- Measure power consumption
 - May vary with different cards, write buffer sizes
- May choose different amounts of logging for testing vs. deployment

- When something goes wrong...what do you do?
- Connectors
 - Can bring USB (or other interface) to outside of box without needing to access interior
 - Or consider an access compartment in enclosure





When things really go wrong

- Sometimes even with careful design, code fails
- How to reset device in the field?



When things really go wrong

- Sometimes even with careful design, code fails
- How to reset device in the field?







EXCLUSIVE

POP CULTURE

EXCLUSIVE: Fyre Festival 2: Dates, location and how to get tickets

"My dream is finally becoming a reality," Billy McFarland, the founder of the controversial festival, told TODAY.

51

- A sentinel that monitors your MCU
- A timer that counts up
- If the timer reaches threshold, it reboots the MCU*
- The MCU code periodically resets the watchdog when it is sure that everything is OK

NATCHDOG TIMER





- Software watchdog
 - A function with ESP.restart() inside it
 - Called when a timer variable goes off
 - Basically useless
 - Don't do this
- Hardware watchdog
 - A distinct internal HW block
 - This is what we'll use
- A separate HW watchdog chip
 - If you **really** want to be safe

```
Serial.print("Attempting to connect to ");
Serial.println(network);
while (WiFi.status() != WL_CONNECTED && count < 6) { //can change thi
    delay(500);
    Serial.print(".");
    count++;
}
delay(2000); //acceptable since it is in the setup function.
if (WiFi.isConnected()) { //if we connected then print our IP, Mac, and
    Serial.println("CONNECTED!");
    delay(500);
} else { //if we failed to connect just Try again.
    Serial.println("Failed to Connect :/ Going to restart");
    Serial.println(WiFi.status());
    ESP.restart(); // restart the ESP (proper way)
```

- Software watchdog
 - A function with esp_restart() inside it
 - Basically useless
 - Don't do this
- Hardware watchdog
 - A distinct internal HW block
 - This is what we'll use
- A separate HW watchdog chip
 - If you **really** want to be safe

Click here for production status of specific part numbers.

MAX6746–MAX6753

μP Reset Circuits with Capacitor-Adjustable Reset/Watchdog Timeout Delay

General Description

The MAX6746–MAX6753 low-power microprocessor (µP) supervisory circuits monitor single/dual system supply voltages from 1.575V to 5V and provide maximum adjustability for reset and watchdog functions. These devices assert a reset signal whenever the V_{CC} supply voltage or RESET IN falls below its reset threshold or when manual reset is pulled low. The reset output remains asserted for the reset timeout period after V_{CC} and RESET IN rise above the reset threshold. The reset function features immunity to power-supply transients.

The MAX6746–MAX6753 have $\pm 2\%$ factory-trimmed reset threshold voltages in approximately 100mV increments from 1.575V to 5.0V and/or adjustable reset threshold voltages using external resistors.

The reset and watchdog delays are adjustable with external capacitors. The MAX6746–MAX6751 contain a watchdog select input that extends the watchdog timeout period by 128x. The MAX6752/MAX6753 contain a window watchdog timer that looks for activity outside an expected window of operation.

The MAX6746–MAX6753 are available with a push-pull or open-drain active-low $\overline{\text{RESET}}$ output. The MAX6746–MAX6753 are available in an 8-pin SOT23 package and are fully specified over the automotive temperature range (-40°C to +125°C).

Applications

- Medical Equipment
- Automotive
- Intelligent Instruments
- Portable Equipment
- Battery-Powered Computers/Controllers
- Embedded Controllers
- Critical µP Monitoring
- Set-Top Boxes
- Computers

Benefits and Features

- Configurable Reset and Watchdog Options Enables Wide Variety of Applications
- Factory-Set Reset Threshold Options from 1.575V to 5V in ~100mV Increments
- Adjustable Reset Threshold Options
- Single/Dual Voltage Monitoring
- Capacitor-Adjustable Reset Timeout
- Capacitor-Adjustable Watchdog Timeout
- Min/Max (Windowed) Watchdog Option
- Manual-Reset Input Option
- Push-Pull or Open-Drain RESET Output Options
- 3.7µA Supply Current Reduces System Power Consumption
- Integrated Power Supply Protection Increases Robustness
- Power-Supply Transient Immunity
- Guaranteed RESET Valid for V_{CC} ≥ 1V
- 8-Pin SOT23 Packages Saves Board Space
- AEC-Q100 Qualified. Refer to <u>Ordering Information</u> for Specific /V Trim Variants

Typical Operating Circuit



Selector Guide and Ordering Information annear at end of

ESP32 watchdog timers

- Four on-board watchdog timers
 - Two main system watchdog timers
 - This is what you'll be using, as the "task watchdog timer" monitoring (on MWDT0)
 - When it fires, will cause core reset
 - There is also an interrupt watchdog timer (on MWDT1) to make sure interrupts don't get blocked
 - If something disables interrupts for too long
 - RTC Watchdog
 - Used during boot to make sure boot occurs quickly enough
 - One low-power "super watchdog" timer
 - Operates independently, looking for feed from CPU every second



Figure 12.1-1. Watchdog Timers Overview

- Not for general error handling
- For catching unanticipated errors
 - ESD, electrical noise, etc.
 - Memory leak causing overflow
- Or things that really shouldn't happen
 - Up to you to decide!

 Accessible via Arduino framework





Note that this format has apparently changed in more recent version of arduino-esp But at least my platformio is using this version 58

- Setting the WDT timeout
- Longer than the longest you expect to go thru your loop
- This can get tricky with
 - Comms: WiFi, cellular, etc.
 - SD card writes
 - etc.

Your projects are not lifethreatening or safety critical... ...err on side of too long

```
#include <Arduino.h>
     #include "esp task wdt.h"
    //3 seconds WDT
     #define WDT_TIMEOUT 3
    #define I2C SDA 4
     #define I2C SCL 5
    Adafruit SHT4x sht4 = Adafruit SHT4x();
11
     int RHT_MEASUREMENT_INTERVAL = 1000;
13 ▼ void setup() {
       Serial.begin(115200);
       Serial.println("Configuring WDT...");
       esp_task_wdt_init(WDT_TIMEOUT, true); //initialize WDT
       esp task wdt add(NULL); //add current thread to WDT watch
```

- Simplest architecture
- Execute each time you go thru your loop
- Simpler, a bit less robust
- Will this catch all the faults you might expect to occur?



- A bit more complex
- Run various checks during your loop
- Only feed WTD if all checks are good
- Make sure this is what you want!
 - Do you really want to reboot if any of these checks are not ok?

```
RTC_DATA_ATTR int wtd_state = 0;
     loop {
         wtd state = 0;
         status = read sensor1();
                                       // returns 1 if OK
         wtd state |= status << 0;
         status = read sensor2();
         wtd_state |= status << 1;</pre>
10
11
12
         status = connect_to_wifi();
         wtd state = status << 2;
13
14
15
16
17
         feed_wtd(wtd_state);
18
     }
19
20
     void feed wtd(int &s) {
21
         if (s == 0b111) {
22
             esp task wdt reset();
23
             s = 0;
24
25
26
```

- What happens during sleep?
- According to block diagram, WDT should be active during light sleep
- But in my testing, it's not!
- Definitely not active during deep sleep

Please test!



Power consumption



Low power consumption components capable of working in Deep-sleep mode

ESP32-C3 Functional Block Diagram

• What to do after WTD timeout?



• What to do after WTD timeout?



Startup Settings

Press a number to choose from the options below:

Use number keys or functions keys F1-F9.

1) Enable debugging
 2) Enable boot logging
 3) Enable low-resolution video
 4) Enable Safe Mode
 5) Enable Safe Mode with Networking
 6) Enable Safe Mode with Command Prompt
 7) Disable driver signature enforcement
 8) Disable early launch anti-malware protection
 9) Disable automatic restart after failure

- What to do after WTD timeout?
- Definitely capture your reboot reason esp_reset_reason()
 - This is an enum that will tell you whether reboot was due to WTD, deepsleep, brownout, power-on, etc.
- Then what?
- Some options
 - Act as if nothing bad happened
 - Go into "safe mode"
 - E.g., wait for firmware update

Bad FW design

- Beware of infinite loops!
 - Unless you are sure that this is what you want to do
 - For example, trigger WTD reset
- Avoid using delays (blocking code)
- Use timers and check

```
wire.begin(12c_SDA, 12c_SCL),
if (! sht4.begin()) {
   Serial.println("Couldn't find SHT4x");
   while (1) delay(1);
}
sht4.setPrecision(SHT4X_HIGH_PRECISION);
```

Bad FW design

- Beware of infinite loops!
 - Unless you are sure that this is what you want to do
 - For example, trigger WTD reset
- Avoid using delays (blocking code)
- Use timers and check

2+ sec delay each time you boot!

```
void setup() {
   Serial.begin(9600); //begin serial
   while (!Serial) {
      delay(100);
   }
```

```
WiFi.begin(network, password);
```

//if using channel/mac specification for crowded bands use the following: //WiFi.begin(network, password, channel, bssid); uint8 t count = 0; //count used for Wifi check times Serial.print("Attempting to connect to "); Serial.println(network); while (WiFi.status() != WL CONNECTED && count < 6) { //can change this to delay(500); Serial.print("."); count++; delay(2000); //acceptable since it is in the setup function. if (WiFi.isConnected()) { //if we connected then print our IP, Mac, and S Serial.println("CONNECTED!"); delay(500); } else { //if we failed to connect just Try again. Serial.println("Failed to Connect :/ Going to restart"); Serial.println(WiFi.status()); ESP.restart(); // restart the ESP (proper way) randomSeed(analogRead(A0)); //"seed" random number generator

Bad FW design

- Beware of infinite loops!
 - Unless you are sure that this is what you want to do
 - For example, trigger WTD reset
- Avoid using delays (blocking code)
- Use timers and check

```
if ((millis() - last_time) > GETTING_PERIOD) { // GETTING_PERIOD since
    sht4.getEvent(&humidity, &temp);// populate temp and humidity object
    float bat = read_analog_voltage(1, 10);
    bat = bat * (47+22.0)/22.0;
    Serial.println(bat);
    //formulate GET request...first line:
    sprintf(request_buffer, "POST http://efpi-10.mit.edu/tunnel_voldman/
    // sprintf(request_buffer, "GET http://numbersapi.com/%d/trivia HTTF
    strcat(request_buffer, "Host: efpi-10.mit.edu\r\n"); //add more to t
    strcat(request_buffer, "\r\n"); //add blank line!
    //submit to function that performs GET. It will return output using
    do_http_GET("efpi-10.mit.edu", request_buffer, response_buffer, OUT_
    last_time = millis();//remember when this happened so we perform new
}
```

Go to sleep!

- ESP clock is 160 MHz → 6 ns/clock tic
- Modem-sleep: ??? to turn off/on radios
- Light sleep: ~320 us to enter, ~500 us to wake
- Deep sleep: ??? to enter, 200+ ms to wake
 - Apparently can be made faster via optimization, down to 10s of ms
- If you don't need radios, turn them off
- If you are doing nothing for more than a few ms, go to light sleep
- If you are doing nothing for more than a few seconds, go to deep sleep

Caveat: these values are from internet (not Espressif) so YMMV

Rebooting

• Sometimes you need to really power cycle

How to power cycle this?



Rebooting

- Sometimes you need to really power cycle
- Put in a reset switch connected to MCU
- Put in a switch connected to battery
- Consider an external option



System variables you may want to track

- Raw and processed data
 - RH, T, wind
 - Object presence/absence over time
 - Timestamped tripwire
 - Images
- Communications parameters
 - SSID, RSSI, etc.
 - Number of failed connection attempts
 - Number of failed POSTs, GETs
- Time How will you know this?

Early on in testing/validation, keep raw-er data Beware of privacy issues!
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ON ALARM DOWN UP SET RESET	J FF

- Raw and processed data
 - RH, T, wind
 - Presence/absence over time
 - Timestamped tripwire
 - Images
- Communications parameters
 - SSID, RSSI, etc.
 - Number of failed connection attempts
- Time
 - Can get time from internet
 - From your server
 - SNTP: Simple Network Time Protocol
 - Can keep time on ESP32
 - RTC timer works thru deep sleep
 - 150 kHz RC oscillator
 - _ . . .

Early on in testing/validation, keep raw-er data Beware of privacy issues!

Anywhere from 1 sec/min to 1 sec/day $_{74}$

System data

- System temperature & RH
 - ESP32C3 has an internal temperature sensor (but I don't think its accessible via Arduino framework)
- Last reset reason
- System memory utilization
 - Memory leak?

heap_caps_get_free_size(MALLOC_CAP_DEFAULT);

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- Battery state
 - In lab01 we measured battery voltage
 - Even better is to measure SOC
 - MAX17048 is a good part for this
 - I2C, one external passive
 - If you are not using LiPo cells, you might need a different fuel gauge!

WiFI provisioning

- If using WiFi, can hardcode credentials
 - This can get annoying if you are deploying in locations with different SSIDs
- Or can put in a set of SSIDs and connect to strongest one that is available
- Or can add code to send credentials to ESP32 over BLE or WiFi
 - Various tutorials exist online
 - https://randomnerdtutorials.com/esp32-wi-fiprovisioning-ble-arduino/

//wifi network credentials for 6.08 Lab (this is a decent 2.4
// char network[] = "608_24G";
// char password[] = "608g2020";



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 - It might have bugs
 - It might need new features
 - It might have a testing variant and a release variant
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 - Last year used: esp32FOTA
 - Others exist

- Store program bin on server
 - With associated JSON telling FW version
- On ESP32
 - Go to server and get JSON
 - Check version against current
 - If update needed, pull new bin
 - Place into new OTA partition
 - Reboot and run new partition FW

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 - Others exist
- They also got it to work with cellular

LoRa? Doubt it...